

Correlation Decay in Random Decision Networks

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MIT

Stochastic Networks 08

Outline

1 Introduction

- Optimization on graphical models
- Motivation
- Correlation Decay
- Previous Work

2 General results

- The tree recursion and the exact cavity recursion
- Implications of Correlation decay on Decentralized Optimization

3 Coupling technique

- How to achieve Correlation decay: A distance-dependent coupling
- Gaussian Costs

4 Density evolution and monotonicity techniques

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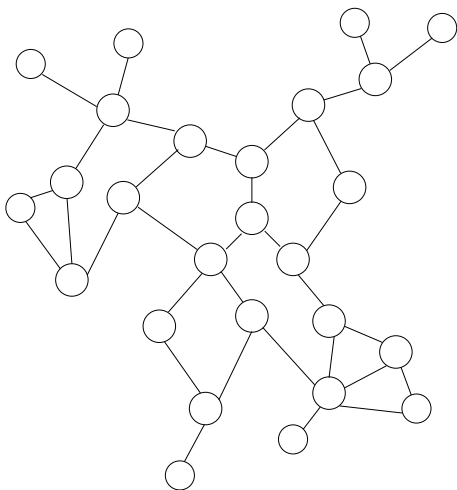
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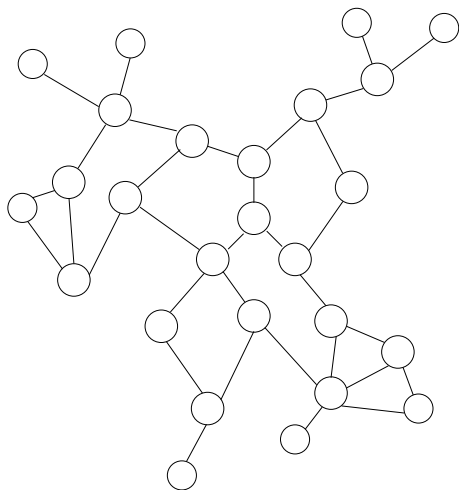
4 Density evolution and monotonicity techniques

Optimization on Graphical Models



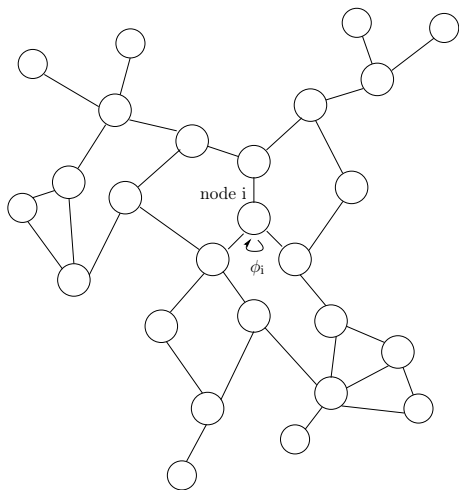
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 - In each node i , decision x_i is made.
 - Cost functions on nodes $\phi_i(x_i)$ and edges $\phi_{i,j}(x_i, x_j)$
 - Objective: find x^* s.t.
$$f(x^*) = \max_x \sum_{i \in V} \phi_i(x_i) + \sum_{(i,j) \in E} \phi_{i,j}(x_i, x_j)$$
 - Our setting: $(\Phi_e), (\phi_i)$ are **random** i.i.d functions.

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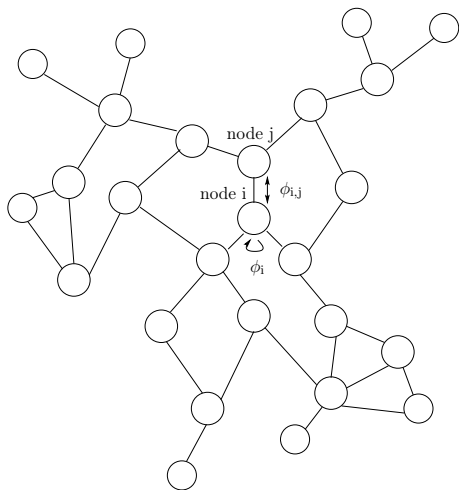
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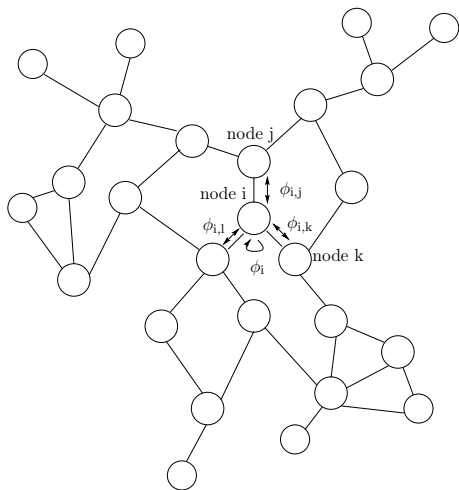
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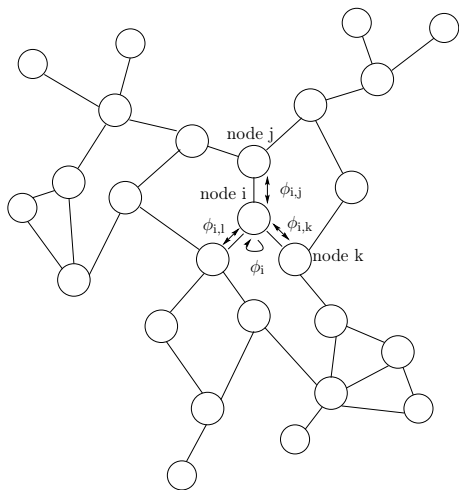
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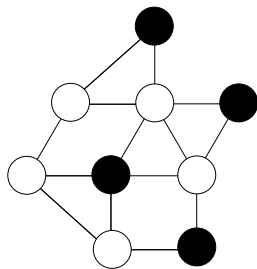
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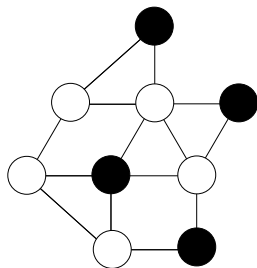
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Combinatorial optimization



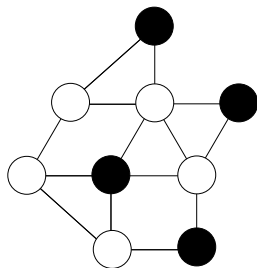
- Graph (V, E) , weights $W \in \mathbb{R}^{|V|}$
- Independent set $U: \forall (u, v) \in E, (u \notin U) \cup (v \notin U)$
- Maximum Weigthed Independent Set: find an independent set U which maximizes $\sum_{u \in U} W_u$
- Decision network formulation: $\Phi_e(1, 1) = -\infty$ for all $e \in E$, and 0 otherwise. $\Phi_u(1) = W_u$ for all $u \in U$

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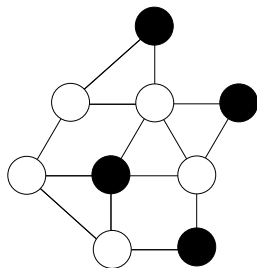
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Some hardness facts

- NP-hard, even for $\Delta = 3$, where $\Delta = \max_{v \in V} |\mathcal{N}_v|$
- **Hastad**[1996] NP-hard to approximate within

$$n^\alpha, \forall \alpha < 1, |V| = n$$

- **Trevisan**[2001] NP-hard to approximate to within

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- **Berman & Karpinski**[1999]. NP-hard to approximate within

$$1.0071 \quad \text{for } \Delta = 3$$

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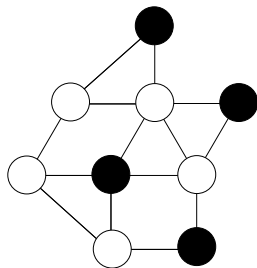
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Contribution



Theorem

Suppose W_u are independent exponential random variables, and $\Delta \leq 3$. Then there exists an EPRAS for solving the MWIS problem: In $O(|V|2^{\epsilon^{-1.1}})$ time, one can find U such that $1 - \epsilon \leq \frac{W^* - W_U}{W^*} \leq 1$

In fact, for any Δ , one can find a distribution such that there exists a FPTAS.

Statistical Inference

- Family of random variables (X_1, \dots, X_n) with factored probability distribution $P(X) = \prod_{(i,j) \in E} \Psi_{i,j}(x_i, x_j) \prod_{i \in V} \Psi_i(x_i)$
- Maximum likelihood problem: Find X which maximizes $P(X)$.
Equivalent to optimization problem on a graph, with $\Phi_{i,j} = \log(\Psi_{i,j})$ and $\Phi_i = \log(\Psi_i)$.
- If $(X_i)_{i \in S}$, where $S \subset \{1, \dots, n\}$ are known :
Maximum likelihood \rightarrow Maximum a posteriori problem
- Edge cost functions are modified by the values of $(X_i)_{i \in S}$

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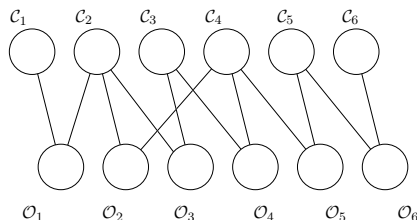
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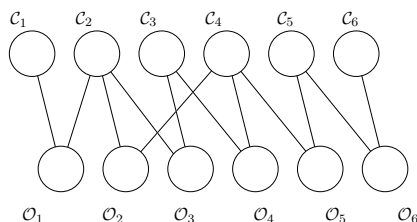
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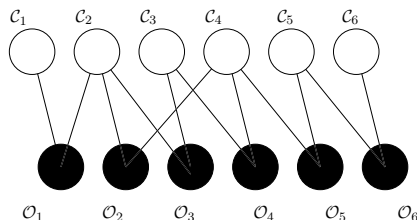
- Probability model: random variable $(C_i)_{i=1,\dots,n}$ and $(O_i)_{i=1,\dots,m}$. Each O_i is connected to a set of parents $\mathcal{P}(i)$ (with $|\mathcal{P}(i)| \leq 2$)
- Probability distribution
$$P(\mathcal{C}, \mathcal{O}) = \prod_{i=1,\dots,n} P(C_i) \prod_{k=1,\dots,m} P(O_k | C_j, j \in \mathcal{P}(k))$$
- MAP is equivalent to a maximization within our framework, with $V = \{C_i\}$, $E = \{\mathcal{P}(i)\}$, $\Psi_i = P(C_i)$ and for any two i, j parents of observation k , $\Psi_{i,j} = \log(P(O_k | C_j, j \in \mathcal{P}(k)))$.
- Since O are random, $\Psi_{i,j}$ is naturally random as well; but the structure of the network is not.

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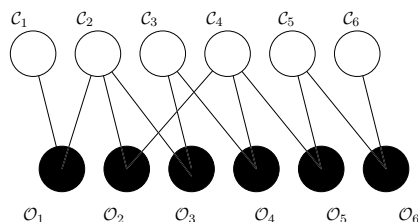
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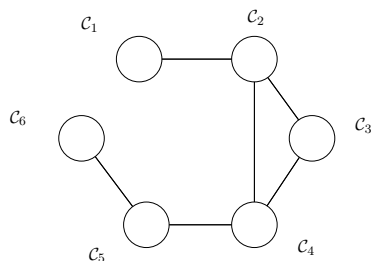
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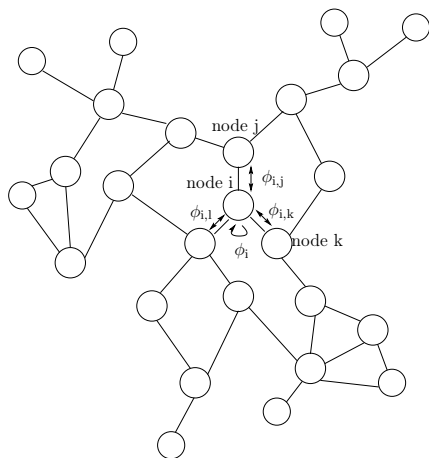
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Decentralized Optimization and Objectives



- Each node i represents an agent which makes a decision x_i
- Agents try to collaborate towards a common objective

Decentralized optimization:

How to find x_i^* for each i , using only local information?

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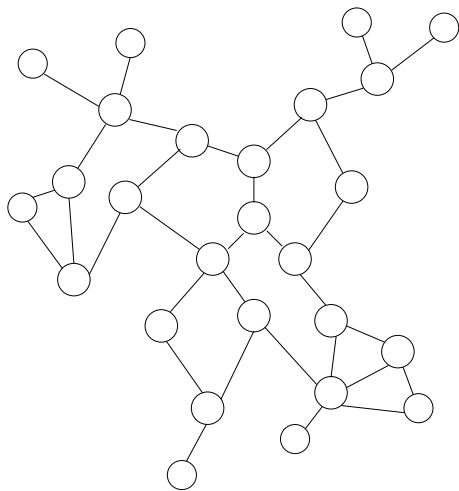
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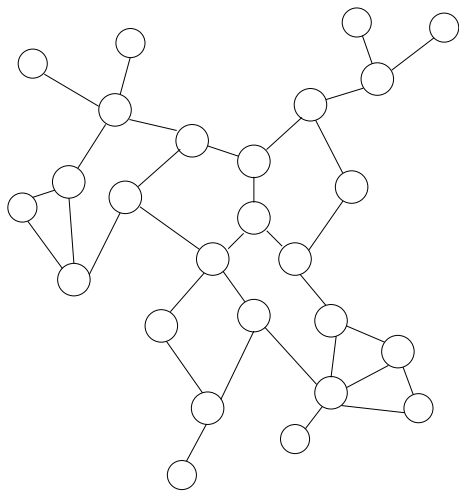
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Correlation decay



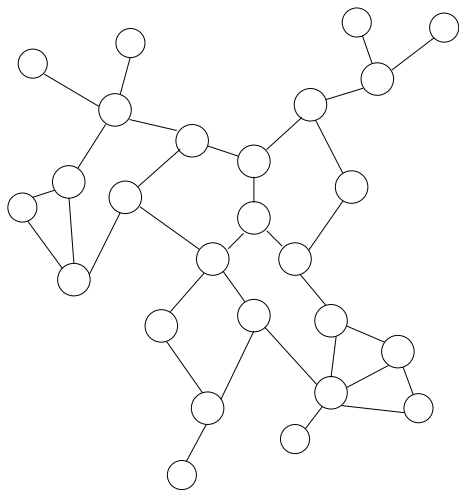
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- Boundary condition at distance k : $B_k = \{x_j, j : d(i, j) \geq k\}$.
- Correlation decay:
 $Z_i(x_i | B_k) \approx Z_i(x_i)$ as $k \rightarrow \infty$.

Correlation decay



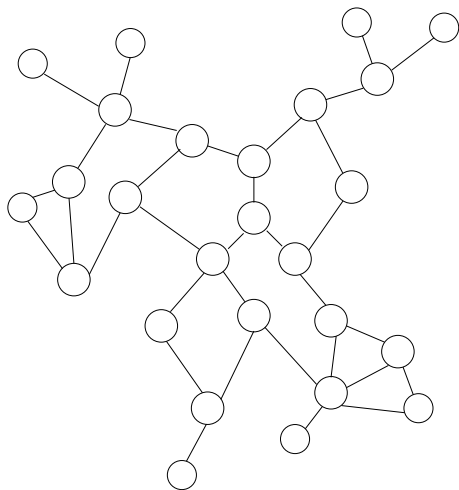
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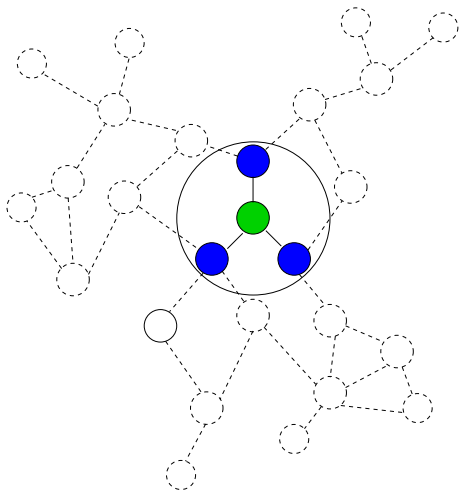
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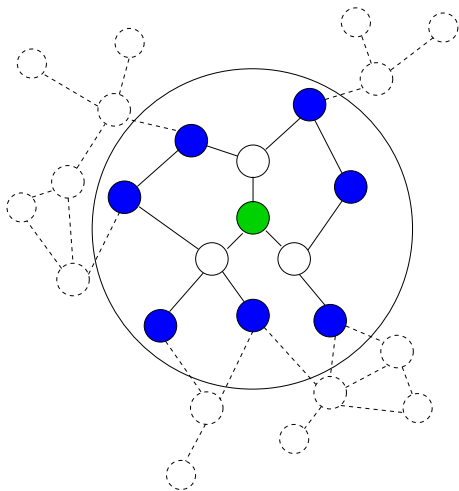
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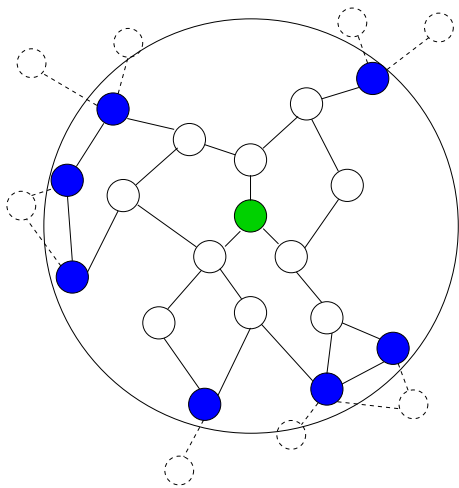
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Contributions

- Cavity Expansion Algorithm (CEA) for optimization on general decision networks
- Correlation Decay implies near-optimality in poly-time for CEA
- Sufficient conditions for correlation decay
- PTAS for Independent set with $\text{Exp}(1)$ weights

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Related work

Decentralized decision making:

- Rusmevichientong & Van Roy (01,03)

Optimization in graphical models:

- Moallemi & Van Roy (06,07)
- Bayati, Sharma, Shah (06)
- Sanghavi & Shah (08)
- Jung & Shah (07)

Bonus-type recursion (“Objective method”)

- Aldous&Steel (02)

Related work

Computation trees, correlation decay

- Bayati, Gamarnik, Katz, Nair, Tetali (07)
- Gamarnik&Katz (07)
- Gamarnik, Nowicki, Swirszcz (05)
- Weitz (06)
- Nair&Tetali (07)

Statistical Physics and cavity algorithm

- Montanari
- Mezard and Montanari (book)

Outline

1 Introduction

- Optimization on graphical models
- Motivation
- Correlation Decay
- Previous Work

2 General results

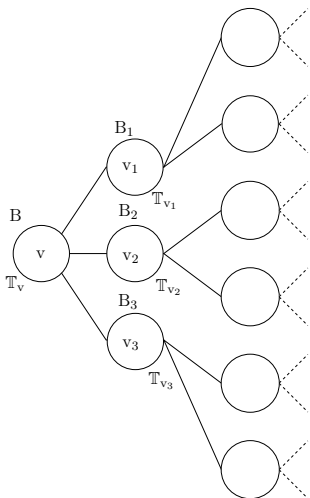
- The tree recursion and the exact cavity recursion
- Implications of Correlation decay on Decentralized Optimization

3 Coupling technique

- How to achieve Correlation decay: A distance-dependent coupling
- Gaussian Costs

4 Density evolution and monotonicity techniques

Bonus and cavity recursion on trees



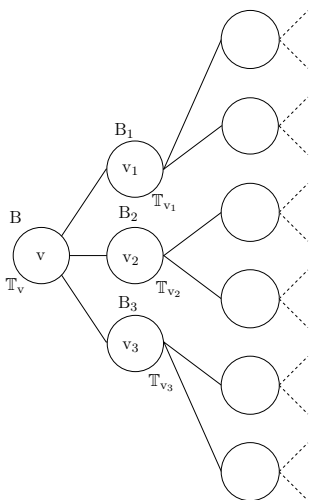
- \mathbb{T}_v subtree rooted at v . $J_v(\mathbf{x})$ the optimal value when decision in v is forced to be \mathbf{x} .
- Recursion: $J_v(1) = \phi_v(1) + \sum_1^d p J(v \leftarrow v_i)$

$$p J(v \leftarrow v_i) = \max(\Phi_{v,v_i}(1, 1) + J_{v_i}(1), \Phi_{v,v_i}(1, 0) + J_{v_i}(0))$$

- Bonus: $B_v \triangleq J_v(1) - J_v(0)$.
- $B_v = \phi_v(1) - \phi_v(0) + \sum_1^d \mu(v \leftarrow v_i)$ where μ (partial bonus or message) is:

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Bonus and cavity recursion on trees



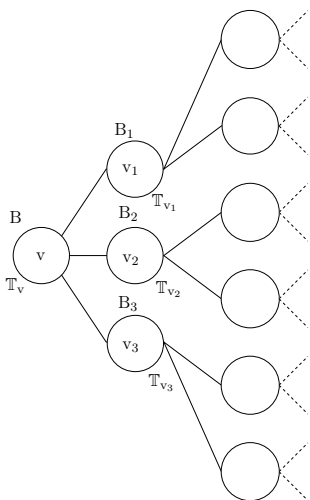
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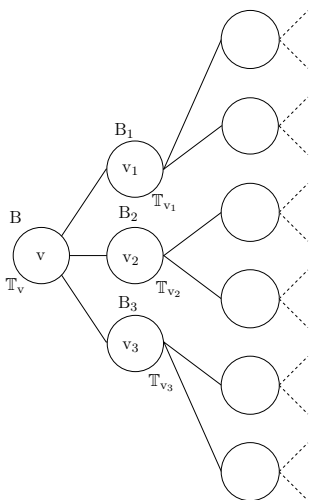
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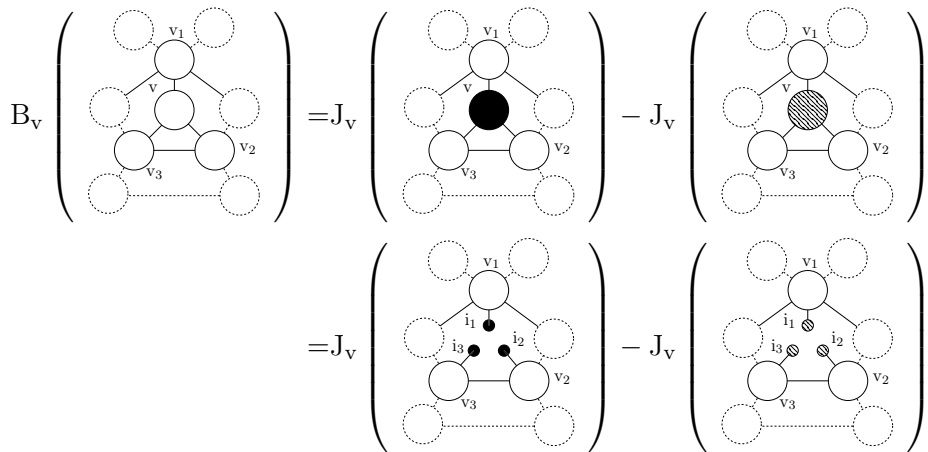
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The cavity recursion on general graphs



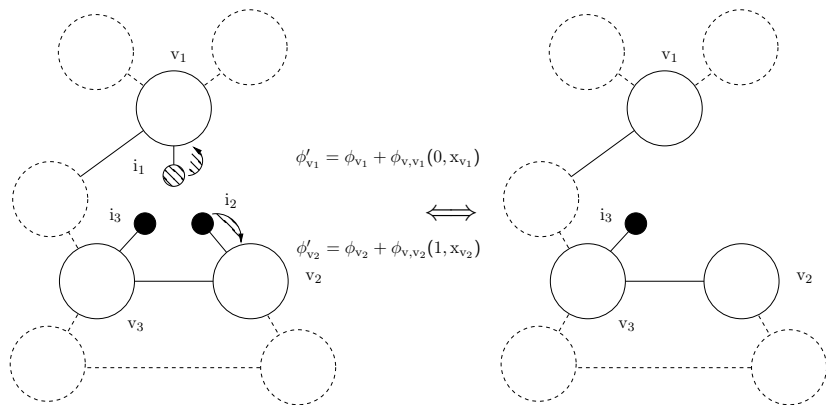
The cavity recursion(continued)

$$\begin{aligned}
 & \mathbf{B}_v = \mathbf{J}_v \left(\begin{array}{c} \text{Diagram 1} \\ \text{Diagram 2} \\ \text{Diagram 3} \end{array} \right) - \mathbf{J}_v \left(\begin{array}{c} \text{Diagram 4} \\ \text{Diagram 5} \\ \text{Diagram 6} \end{array} \right) \\
 & + \mathbf{J}_v \left(\begin{array}{c} \text{Diagram 7} \\ \text{Diagram 8} \\ \text{Diagram 9} \end{array} \right) - \mathbf{J}_v \left(\begin{array}{c} \text{Diagram 10} \\ \text{Diagram 11} \\ \text{Diagram 12} \end{array} \right) \\
 & + \mathbf{J}_v \left(\begin{array}{c} \text{Diagram 13} \\ \text{Diagram 14} \\ \text{Diagram 15} \end{array} \right) - \mathbf{J}_v \left(\begin{array}{c} \text{Diagram 16} \\ \text{Diagram 17} \\ \text{Diagram 18} \end{array} \right)
 \end{aligned}$$

The diagrams are arranged in a 3x2 grid. Each diagram shows a central node v_1 connected to three nodes i_1, i_2, i_3 , which are in turn connected to three nodes v_2, v_3 . The nodes v_2, v_3 are connected to each other and to a set of external nodes (represented by dashed circles). The diagrams illustrate the cavity recursion by showing the effect of removing a node and its incident edges, and then adding it back.

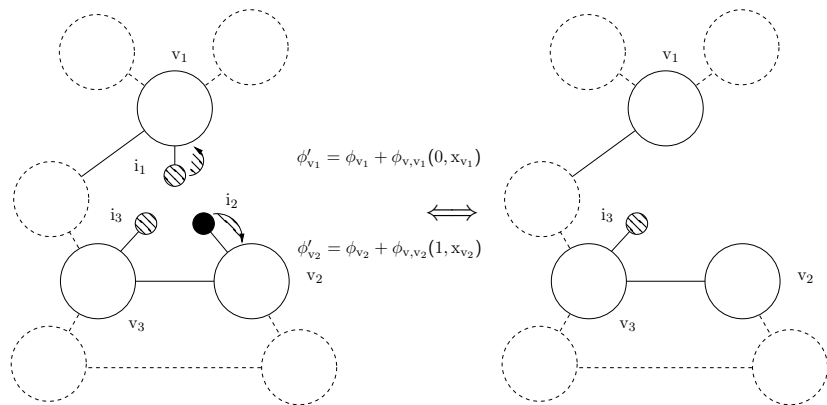
The cavity recursion(continued)

Note:



The cavity recursion(continued)

And:



The cavity recursion(continued)

Defining $\mu(v \leftarrow v_3)$ as

$$J_v \left(\begin{array}{c} \text{Diagram 1} \\ \text{Diagram 2} \end{array} \right) - J_v \left(\begin{array}{c} \text{Diagram 3} \\ \text{Diagram 4} \end{array} \right)$$

The diagrams show a tree structure with nodes v_1 , v_3 , and v_2 . Node v_3 is the child of v_1 , and v_2 is the child of v_3 . Dashed circles represent other nodes in the tree. In the first diagram, node v_3 has a solid black dot. In the second diagram, node v_3 has a hatched dot.

We obtain a recursion:

$$B_v = \phi_v(1) - \phi_v(0) + \sum_1^d \mu(v \leftarrow v_i)$$

If B_{v_i} is the bonus of v_i in the **modified graph**, then we have the partial bonus equation:

$$\begin{aligned} \mu(v \leftarrow v_i) = & \max(\Phi_{v,v_i}(1, 1) + B_{v_i}, \Phi_{v,v_i}(1, 0)) \\ & - \max(\Phi_{v,v_i}(0, 1) + B_{v_i}, \Phi_{v,v_i}(0, 0)) \end{aligned}$$

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Correlation decay

Definition (Correlation decay)

Let B be the bonus in the node, and B^r the approximation of the bonus resulting from the depth r cavity recursion. We say that correlation decay occurs if there exists $K_c \geq 0, \alpha_c < 1$ such that

$$E|B^r - B| \leq K_c \alpha_c^r$$

Theorem (Correlation decay implies decentralized optimum)

Suppose the system exhibits correlation decay with parameters K_c, α_c and has bounded degree Δ . Consider $\epsilon > 0$. If $r > P(|V|, \ln(\epsilon), \ln(\frac{1}{1-\alpha_c}))$ and $x_i = 1_{B^r > 0}$ (computable in poly time), then

$$P(x \text{ is optimal}) > 1 - \epsilon$$

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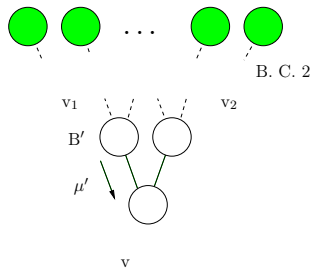
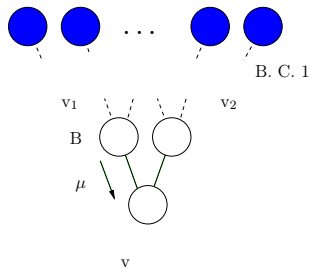
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Coupling technique



Definition

The network experiences coupling with parameters (a, b) if for any edge of the computation tree, we have

$$P(\mu = \mu' \mid B, B') \geq (1 - a) - b|B - B'|$$

Theorem

Suppose that the network exhibits coupling with parameters (a, b) and has degree bounded by Δ . Then, if

$$a(\Delta - 1) + \sqrt{4bK}(\Delta - 1)^{3/2} < 1 \quad (1)$$

the network experiences exponential correlation decay.

Suppose additionally that the network is triangle free and that for cost functions are symmetric. Then, if

$$(\Delta - 1)(a + \sqrt{4bK}) < 1 \quad (2)$$

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Gaussian costs

- Example: zero cost on nodes, Gaussian cost on edges:

$$f \sim \mathcal{N}(\vec{\mu} = \begin{pmatrix} \mu_{00} = 0 \\ \mu_{01} = 0 \\ \mu_{10} = 0 \\ \mu_{11} = 0 \end{pmatrix}, C = \begin{pmatrix} 1 & \alpha & \alpha & -\alpha \\ \alpha & 1 & -\alpha & \alpha \\ \alpha & -\alpha & 1 & \alpha \\ -\alpha & \alpha & \alpha & 1 \end{pmatrix})$$

Theorem (Sufficient condition for correlation decay)

Suppose

$$\frac{1}{3} - \frac{2\pi}{9\Delta} < \alpha < 1/3$$

Then decay of correlation occurs.

Gaussian costs

More generally:

- Let $X = \Phi(1, 1) - \Phi(0, 0) - \Phi(0, 1) + \Phi(1, 0)$,
 $Y = (\Phi(1, 1) + \Phi(0, 0) - \Phi(0, 1) - \Phi(1, 0))$.
- Define $\beta = \beta_1 + \beta_2$, where:

$$\beta_1 = \frac{2}{\pi \sqrt{1 - \rho^2}} \frac{\sigma_Y}{\sigma_X}$$

and

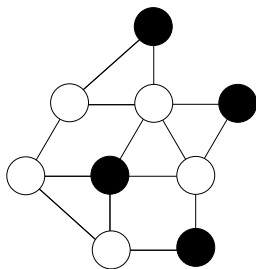
$$\beta_2 = \sqrt{\frac{2}{\pi}} \frac{1}{\sqrt{(1 - \rho^2)}} \frac{E|Y|}{\sigma_X}$$

Theorem (Condition for correlation decay)

Then correlation decay occurs provided

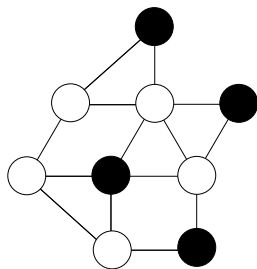
$$\Delta(\beta + \sqrt{\Delta\beta}) < 1$$

Cavity and bonus recursion



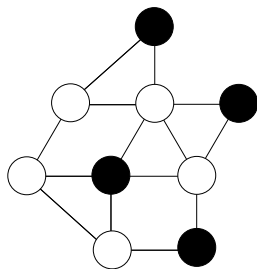
- Decision network formulation: $\Phi_e(1, 1) = -\infty$ for all $e \in E$, and 0 otherwise. $\Phi_u(1) = W_u$ for all $u \in U$
- Message equation:
$$\mu(B_j) = \max(\Phi_j(1, 1) + B_j, \Phi_j(1, 0)) - \max(\Phi_j(0, 1) + B_j, \Phi_j(0, 0))$$
- For IS: $\mu(B_j) = -\max(0, B_j)$ and so $B = W - \sum_j \max(0, B_j)$
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Cavity and bonus recursion



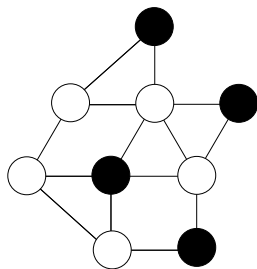
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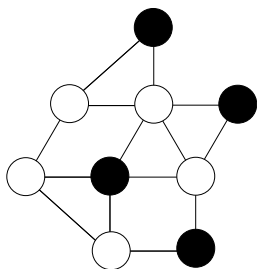
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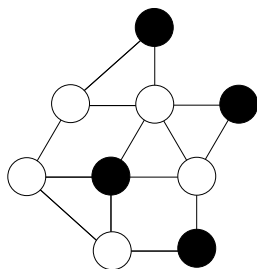
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Density evolution



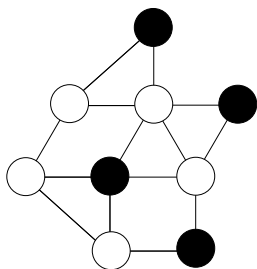
- $\tilde{B} = \max(0, W - \sum_j \tilde{B}_j)$
- W and $\sum_j \tilde{B}_j$ are independent, even for general graphs (subtree independence property)
- Assume $W \sim \text{Exp}(1)$. Conditional on $\sum_j \tilde{B}_j = x$, if $W < x$, then $\tilde{B} = 0$, otherwise, $\tilde{B} = W - x$ is exponential
- Therefore, \tilde{B} is always the mixture of a mass in 0 and an exponential random variable

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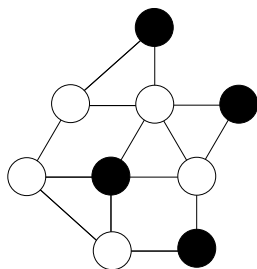
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Correlation decay in Independent Sets

- Let v be a node, and v_1, v_2 its neighbors in the graph.
- $\tilde{B}_v = \max(0, W - \tilde{B}_{v_1} - \tilde{B}_{v_2})$
- Let $M_v = \exp(-B_v)$ and $x = \tilde{B}_{v_1} + \tilde{B}_{v_2}$
- Then:

$$\begin{aligned}E[M_v|x] &= P(W_v \leq x)e^0 + P(W_v > x)E[e^{W_v - x} | W_v > x] \\ &= (1 - e^{-x}) + e^{-x} \frac{1}{2} \\ &= 1 - \frac{1}{2}e^{-x} \\ E[M_v] &= 1 - \frac{1}{2}E[M_{v_1}M_{v_2}]\end{aligned}$$

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Correlation decay in Independent Sets

- Consider two extreme boundary conditions $+$ ($B_{BC}^+ = +\infty$) and $-$ ($B_{BC}^- = 0$)
- $M_v^+ = \exp(-B_v^+)$ and $M_v^- = \exp(-B_v^-)$
- We also have:

$$E[M_v^+] = 1 - \frac{1}{2}E[M_{v_1}^+ M_{v_2}^+]$$

$$E[M_v^-] = 1 - \frac{1}{2}E[M_{v_1}^- M_{v_2}^-]$$

- Combining equations:

$$E[|M_v^+ - M_v^-|] \leq \max(E|M_{v_1}^+ - M_{v_1}^-|, |M_{v_2}^+ - M_{v_2}^-|)$$

- In general, if v had $d \leq 2$ neighbors:

$$E[|M_v^+ - M_v^-|] \leq \frac{d}{2} \max_{1 \leq i \leq d} (E|M_{v_i}^+ - M_{v_i}^-|)$$

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Correlation decay in Independent Sets

- Consider two extreme boundary conditions $+$ ($B_{BC}^+ = +\infty$) and $-$ ($B_{BC}^- = 0$)
- $M_v^+ = \exp(-B_v^+)$ and $M_v^- = \exp(-B_v^-)$
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$$E[M_v^+] = 1 - \frac{1}{2}E[M_{v_1}^+ M_{v_2}^+]$$

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- Remove a very small fraction δ of the neighbors.
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Summary

- Correlation decay implies near-optimal decentralization
- A specific form of coupling can induce correlation decay
- Sufficient conditions can be computed for various problems
- **Message:** Stochasticity can make optimization easier

- Ongoing work
 - Game theoretical or dynamical versions of the problem
 - More general characterizations of conditions for correlation decay

Proof outline

- Bonus equations:

$$B = \Phi(1) - \Phi(0) + \sum_j \mu_j \quad B' = \Phi(1) - \Phi(0) + \sum_j \mu'_j$$

- Continuity of messages: $|\mu_j - \mu'_j| \leq |B_j - B'_j|$
- Coupling event C_j : $|\mu_j - \mu'_j| \leq 1/C_j |B'_j - B_j|$
- This leads to

$$E|B - B'| \leq \sum_j aE|B_j - B'_j| + bE|B_j - B_j|^2$$

- Let e_r be the maximum error for depth r
- Problem-dependent approaches (gaussian costs, bounded functions) allow to convert the inequality into:

$$e_r \leq a'e_{r-1} + b'e_{r-2}$$

- If $\sqrt{a'^2 + 4b'} < 1$ then correlation decay occurs

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- For any j , the partial bonus has the following form:

$$\mu = A_j^3 + \max(B_j, A_j^1) - \max(B_j, A_j^2)$$

where

$$A^1 = \Phi_{u,v_j}(1, 0) - \Phi_{u,v_j}(1, 1)$$

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- **Consequence:** If both B_j, B'_j are greater than A_j^1 and A_j^2 , or smaller than A_j^1 and A_j^2 , then $|\mu - \mu'| = 0$ ("coupling occurs")
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